

Lecture 4: Periodic Orbits in the Plane

Overview:

- Bendixson's Thm
- Poincaré-Bendixson Thm
- Index Theory

Remarks:

- ① The divergence of a continuously differentiable vector field $f(x)$ for $x \in \mathbb{R}^n$ is defined as:

$$\operatorname{div}(f(x)) = \nabla \cdot f(x) = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right) \cdot (f_1, \dots, f_n) = \sum_{i=1}^n \frac{\partial f_i}{\partial x_i}$$

- ② Hyperbolic Equilibria \Leftrightarrow eigs of A w/ no real part

Periodic Orbits in the Plane

Two conditions:

- ① Bendixson's

(absence of periodic orbits)

\rightarrow If $\operatorname{div}(f(x)) \neq 0 \quad \forall x \in D$ & does not change sign, then D contains no periodic orbits

- ② Poincaré-Bendixson \leftarrow only apply to things in the plane
(existence of periodic orbits)

Suppose M is compact (closed & bounded) and positively invariant for the planar, time invariant system $\dot{x} = f(x) \quad x \in \mathbb{R}^2$

If M contains no equilibrium points

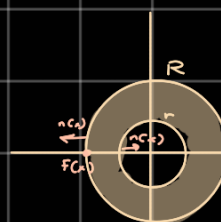
\Rightarrow it contains a periodic orbit

example: ^{Poincaré-Bendixson} Harmonic oscillator

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$\dot{x}_1 = -x_2$$

$$\dot{x}_2 = x_1$$



dynamics

For $R > r > 0$, the ring

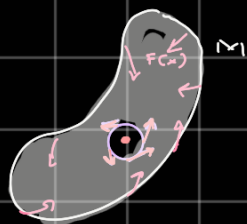
$$\{x : r^2 \leq x_1^2 + x_2^2 \leq R^2\}$$

is compact, invariant, contains no equilibrium \Rightarrow at least 1 periodic orbit (we know there are actually many in this case)

If "no equilibrium" condition in the P.B. thm can be relaxed as

"If M contains one equilibrium which is an unstable focus or unstable node"

Pf sketch:



"carving out the interior"

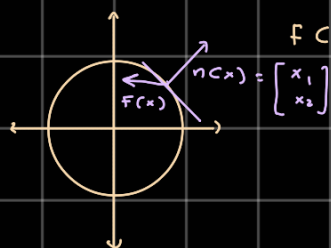
Since the equilibrium is an **unstable focus/node**, we can **encircle it** with a small closed curve on which **$f(x)$** points outward. Then, the set obtained from **M** by carving out the interior of the closed curve is positively invariant & contains no equilibrium

example

$$\dot{x}_1 = x_1 + x_2 - x_1(x_1^2 + x_2^2)$$

$$\dot{x}_2 = -2x_1 + x_2 - x_2(x_1^2 + x_2^2)$$

→ show $B_r \triangleq \{x \mid x_1^2 + x_2^2 \leq r^2\}$ is positively invariant for sufficiently large r (ie $f(x) \cdot n(x) \leq 0$)



$$f(x) \cdot n(x) = \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$= x_1^2 + x_1 x_2 - x_1^2(x_1^2 + x_2^2) - 2x_1 x_2 + x_2^2 - x_2^2(x_1^2 + x_2^2)$$

$$= -x_1 x_2 + (x_1^2 + x_2^2) - (x_1^2 + x_2^2)^2$$

recall

$$|2x_1 x_2| \leq x_1^2 + x_2^2$$

$$\leq \frac{1}{2}(x_1^2 + x_2^2) + (x_1^2 + x_2^2) - (x_1^2 + x_2^2)^2$$

$$= \frac{3}{2}r^2 - r^4$$

$$\Rightarrow f(x) \cdot n(x) \leq \frac{3}{2}r^2 - r^4 \leq 0 \quad \text{if } r^2 \geq \frac{3}{2}$$

$\Rightarrow B_r$ positively invariant for $r \geq \sqrt{\frac{3}{2}}$ and contains the equilibrium $x=0$

$$\frac{\partial f}{\partial x} \Big|_{x=0} = \begin{bmatrix} 1 & 1 \\ -2 & 1 \end{bmatrix} \quad \lambda_{1,2} = 1 \pm j\sqrt{2} \quad \text{unstable focus}$$

$\Rightarrow B_r$ must contain a periodic orbit

A more general form of Poincaré-Bendixon theorem states that for time-invariant planar systems, bounded trajectories converge to equilibria, periodic orbits, or unions of equilibria connected by trajectories.

Corollary: No chaos for time-invariant planar systems

has parallels to winding theory

Index Theory (only applicable to planar systems)

index: the index of a closed curve is K if, when traversing the curve in one direction, $F(x)$ rotates by $2\pi K$ in the same direction. The index of an equilibrium is defined to be the index of a small curve around it that doesn't enclose another equilibrium.

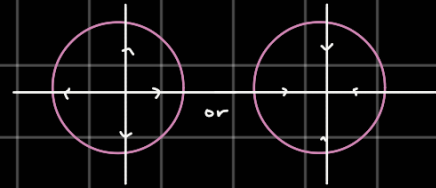
type of equilibrium / curve

index

• node, focus, center

+1

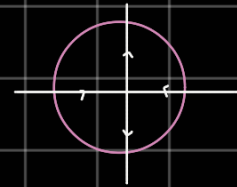
one rotation in same direction



• saddle

-1

as you follow the curve,



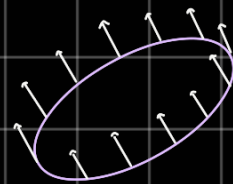
• any closed orbit

+1



• a closed curve not enclosing any equilibria

0



Thm: index of a closed curve is equal to the sum of the indices of the equilibria inside

Corollary: Inside any periodic orbit there must be at least one equilibrium and the indices of the equilibria enclosed must add up to $+1$